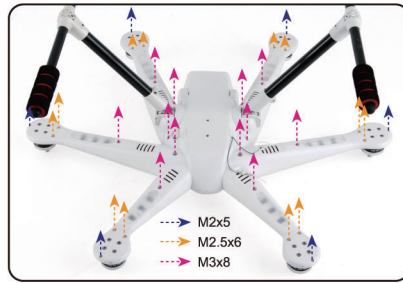
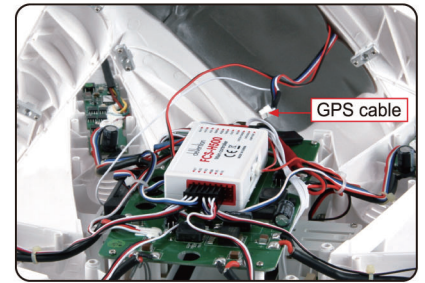


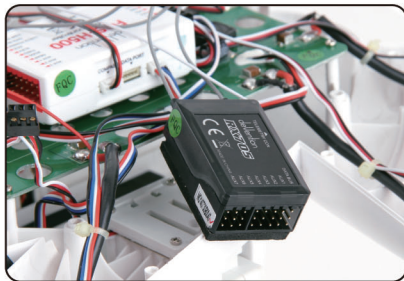
1. Prepare: 1pc TALI H500 model, 1pc 2.4G Bluetooth Datalink 【BT-2401A(BT-2402A)】 (attached dual adhesive tape), 2pcs Connect wire.



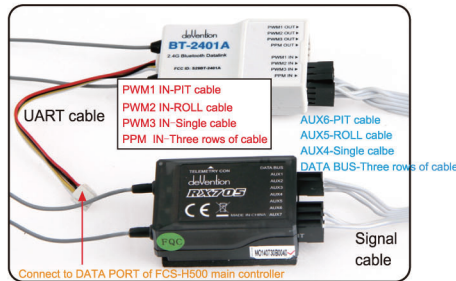
2. Take down propellers and 6pcs M2x5 screw, 12pcs M2.5x6, 12pcs M3x8 at the bottom of TALI H500, put them aside for future use.



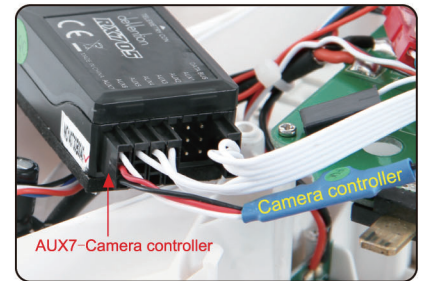
3. Take down the upper cover of TALI H500 and the connect wire which connected FCS-H500 main controller with GPS port.



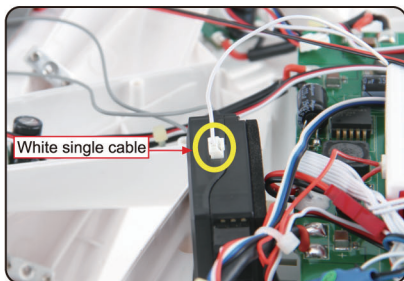
4. Take down all connecting wire of RX705(RX708), then take out RX705(RX708) receiver.



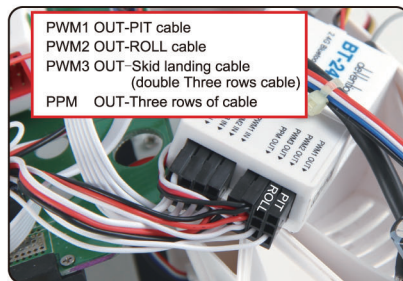
5. Using signal cable to connect BT-2401A(BT-2402A) with RX705(RX708) receiver.



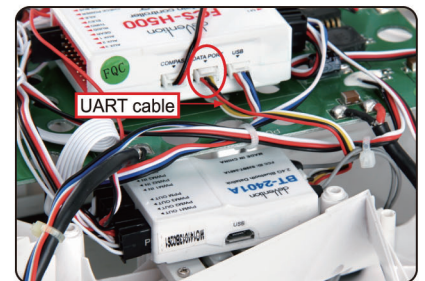
6. Reconnect the camera controller with AUX7 on the RX705(RX708).



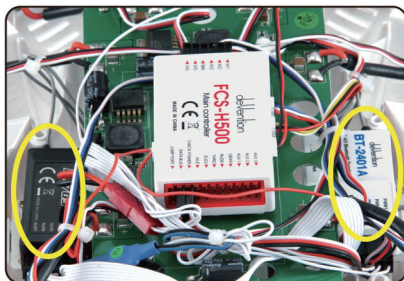
7. Reconnect the white single cable with TELEMETRY CON on the RX705(RX708) and fix the receiver.



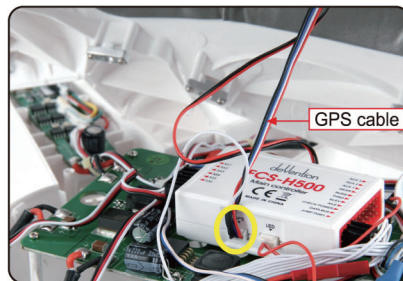
8. Connect the gimbal cable (used to connect receiver), DATA BUS cable and cable for skid landing to BT-2401A(BT-2402A).



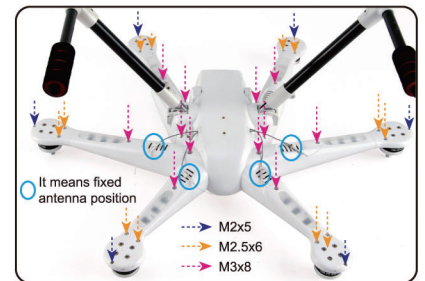
9. Connect UART cable to the DATA PORT of FCS-H500 main controller, and fix the BT-2401A (BT-2402A) ready.



10. The installation instruction map of RX705(RX708) receiver and BT-2401A(BT-2402A).



11. Connect GPS cable to GPS port of FCS-H500 main controller again.



12. Use cable to fix the antenna of RX705(RX708) receiver and BT-2401A(BT-2402A) to the bottom of the TALI H500, then put on the top cover. Install the 6pcs of M2x5, 12pcs of M2.5x6, 12pcs of M3x8 screw again, and then install the propellers.